

MARIA ŻUREK-ETGENS

## On extension of a solution of the translation equation

The main objective of this paper is to give a necessary and sufficient condition for the extensibility of a solution of the translation equation from a substructure  $R$  of an Ehresmann groupoid  $(E; \cdot)$  onto the whole groupoid  $(E; \cdot)$ , without an extension of the fibre  $\Gamma$ . The substructure  $R$  satisfies the condition  $R \cup R^{-1} = E$ .

1. Let  $E$  be an arbitrary non-empty set and let " $\cdot$ " be an arbitrary partial mapping from the set  $E \times E$  into the set  $E$ . A pair  $(E; \cdot)$  will be called a multiplicative system. The domain of the partial mapping " $\cdot$ " will be denoted by  $D$ . Let us define the following set

$$E^0 = \{e \in E: (e, e) \in D. \wedge e \cdot e = e\}.$$

We start with the following definitions.

DEFINITION 1. A multiplicative system  $(E; \cdot)$  is an Ehresmann groupoid if the following conditions are fulfilled:

- (1)  $E^0 = \left\{ e \in E : \bigwedge_{x \in E} [(x, e) \in D. \Rightarrow x \cdot e = x] \wedge \right.$   
 $\left. \wedge [(e, x) \in D. \Rightarrow e \cdot x = x] \right\},$
- (2)  $\bigwedge_{x, y, z \in E} (x, y) \in D. \wedge (y, z) \in D. \Rightarrow (x, y \cdot z) \in D. \wedge$   
 $\wedge (x \cdot y, z) \in D.,$
- (3)  $\bigwedge_{x, y, z \in E} (x, y) \in D. \wedge (x \cdot y, z) \in D. \Rightarrow (y, z) \in D.,$
- (4)  $\bigwedge_{x, y, z \in E} (y, z) \in D. \wedge (x, y \cdot z) \in D. \Rightarrow (x, y) \in D.,$
- (5)  $\bigwedge_{x, y, z \in E} (x, y) \in D. \wedge (y, z) \in D. \Rightarrow x \cdot (y \cdot z) = (x \cdot y) \cdot z,$
- (6)  $\bigwedge_{x \in E} \bigvee_{x \cdot e, e \cdot x \in E^0} (x \cdot e, x) \in D. \wedge (x, e \cdot x) \in D.,$
- (7)  $\bigwedge_{x \in E} \bigvee_{x^{-1} \in E} (x^{-1}, x) \in D. \wedge (x, x^{-1}) \in D. \wedge$   
 $\wedge x^{-1} \cdot x = e_x \wedge x \cdot x^{-1} = {}_x e.$

In the sequel  ${}_x e$  will be called a left unit of the element  $x$  and  $e_x$  will be called a right unit of the element  $x$ . The symbol  $x^{-1}$  will denote an inverse element.

DEFINITION 2. A set  $A \subset E$  is a substructure of the groupoid  $(E; \cdot)$  if and only if  $A \cdot A \subset A$ , where

$$A \cdot A := \left\{ z \in E : \bigvee_{x, y \in A} (x, y) \in D. \wedge z = x \cdot y \right\}.$$

If  $A$  is a substructure of the Ehresmann groupoid  $(E; \cdot)$  then  $A^{-1} := \{x \in E: x^{-1} \in A\}$ , where  $x^{-1}$  is an inverse element.

2. Let  $\Gamma$  be a non-empty set and suppose that  $(E; \cdot)$  is a multiplicative system. Let  $F: \Gamma \times E \rightarrow \Gamma$  be a mapping with the domain  $D_F \subset \Gamma \times E$  and the image  $\mathcal{D}_F \subset \Gamma$ . Let us put

$$Z_F := \left\{ (\alpha, x, y) \in \Gamma \times E^2: (\alpha, x) \in D_F \wedge (F(\alpha, x), y) \in D_F \wedge \right. \\ \left. \wedge (x, y) \in D \wedge (\alpha, x \cdot y) \in D_F \right\}.$$

DEFINITION 3. A mapping  $F: \Gamma \times E \rightarrow \Gamma$  is a solution of the translation equation if

$$\bigwedge_{(\alpha, x, y) \in \Gamma \times E^2} (\alpha, x, y) \in Z_F \implies F(F(\alpha, x), y) = F(\alpha, x \cdot y).$$

DEFINITION 4. Let  $A$  be substructure of the groupoid  $(E; \cdot)$ . A solution of the translation equation  $F: \Gamma \times A \rightarrow \Gamma$  is extendable if there exists a solution  $\bar{F}$  of the translation equation which is defined on the whole set  $\Gamma \times E$  and  $\bar{F}|_{\Gamma \times A} = F$ .

The mapping  $\bar{F}$  is called an extension of the solution  $F$ .

DEFINITION 5. A mapping  $F: \Gamma \times E \rightarrow \Gamma$  satisfies the identity condition if

$$\bigwedge_{\alpha \in \Gamma} \bigwedge_{e \in E^0} (\alpha, e) \in D_F \implies F(\alpha, e) = \alpha.$$

We shall prove the following

THEOREM 1. Let  $(E; \cdot)$  be an Ehresmann groupoid and let  $\Gamma$  be a non-empty set. The solution  $F: \Gamma \times E \rightarrow \Gamma$

of the translation equation satisfies the identity condition if and only if  $F(\cdot, x)$  is a bijection from the set  $\Gamma$  onto the set  $\Gamma$  for every  $x \in E$ .

**P r o o f.** If the mapping  $F(\cdot, x)$  is a bijection from  $\Gamma$  onto  $\Gamma$  for every  $x \in E$  then

$$\bigwedge_{\alpha \in \Gamma} \bigvee_{\beta \in \Gamma} F(\beta, e) = \alpha$$

for every fixed  $e \in E^0$ . Therefore  $F(\alpha, e) = F(F(\beta, e), e) = F(\beta, e) = \alpha$  for an arbitrary  $\alpha \in \Gamma$  and  $e \in E^0$ .

Now, assume that  $\alpha, \beta \in \Gamma$  and  $F(\alpha, x) = F(\beta, x)$  for a fixed  $x \in E$ . Hence  $F(F(\alpha, x), x^{-1}) = F(F(\beta, x), x^{-1})$  thus  $F(\alpha, x \cdot x^{-1}) = F(\beta, x \cdot x^{-1})$  or  $F(\alpha, e) = F(\beta, e)$ , this means that  $\alpha = \beta$ . Moreover for an arbitrary  $x \in E$  and  $\alpha \in \Gamma$  there exists  $\beta = F(\alpha, x^{-1})$  such that  $F(\beta, x) = F(F(\alpha, x^{-1}), x) = F(\alpha, e_x) = \alpha$ . Consequently  $F(\cdot, x)$  is a bijection from  $\Gamma$  onto  $\Gamma$  for every  $x \in E$ , which completes the proof.

The above theorem is not true if the multiplicative system  $(E; \cdot)$  has no inverse elements.

**R e m a r k 1.** If  $F: \Gamma \times E \rightarrow \Gamma$  is a solution of the translation equation and  $(E; \cdot)$  is a multiplicative system without inverse elements then the property

$$\bigwedge_{x \in E} F(\cdot, x): \Gamma \xrightarrow{\text{bij}} \Gamma$$

is only a sufficient condition for  $F$  to fulfil the identity condition.

This fact may be seen from the following



**E x a m p l e.** Let  $\Gamma$  be the set  $\mathbb{R}^+$  of non-negative real numbers. Take  $E = \{(x,y) \in \mathbb{R}^2 : x \leq y\}$ . In the set  $E$  we define the operation  $\circ$  as follows:

$((x,y), (z,t)) \in D$ . iff  $y = z$  and then  $(x,y) \circ (z,t) = (x,t)$ .  
 Let us put  $F(\alpha, x, y) = \alpha + y - x$  for  $\alpha \in \mathbb{R}^+$  and  $(x,y) \in E$ . This function  $F: \mathbb{R}^+ \times E \rightarrow \mathbb{R}^+$  is a solution of the translation equation and  $F$  satisfies the identity condition, but for  $x < y$  we have  $F(\mathbb{R}^+ \times \{x,y\}) = \langle y-x, \infty \rangle \neq \mathbb{R}^+$ .

3. A. Grząślewicz has give in [1] the following theorem concerning the extensibility of a solution of the equation

$$(1) \quad H_1(x) \circ H_2(y) = H_3(x \cdot y).$$

Let  $(E; \circ)$  be an Ehresmann groupoid and let  $R$  be its substructure. If the triplet of functions  $(H_1, H_2, H_3) \in [R \rightarrow E_1]^3$  <sup>\*/</sup>, where  $(E_1; \circ)$  is an Ehresmann groupoid and  $R \cup R^{-1} = E$ , is the solution of the equation (1), then there exists an extension of this solution on the triplet of sets  $(E, E, E)$ , and it is assigned in an unique manner:

$$H_i(x) := \begin{cases} H_i(x) & \text{for } x \in R, \\ H_i(x \cdot e) \circ [H_i(x^{-1})]^{-1} \circ H_i(e_x) & \text{for } x \in R^{-1}, \end{cases}$$

where  $i = 1, 2, 3$ .

Setting  $H_1 = H_2 = H_3$  and treating  $(E_1; \circ)$  as a set

---

<sup>\*/</sup> The symbol  $[X \rightarrow Y]$  denotes a set of all functions  $F$  for which  $D_F \subset X$  and  $Q_F \subset Y$ .

of bijections of the fixed set  $\Gamma$  endowed with composition of functions we can consider equation (1) as the translation equation  $F(F(\cdot, x), y) = F(\cdot, x y)$ , where  $F: \Gamma \times R \rightarrow \Gamma$  and for every  $x \in E$  the function  $F(\cdot, x) = H_1(x)$  is a bijection from the set  $\Gamma$  onto itself. Considering additionally Remark 1 we get the following

**COROLLARY.** If  $F: \Gamma \times R \rightarrow \Gamma$ , where  $R$  is a substructure of Ehresmann groupoid  $(E; \cdot)$  such that  $R \cup R^{-1} = E$  and  $\Gamma$  is an arbitrary fixed set, is a solution of the translation equation such that  $F(\cdot, x): \Gamma \xrightarrow{\text{bij}} \Gamma$  for every  $x \in R$  then  $F$  can be uniquely extended to the solution  $\bar{F}: \Gamma \times E \rightarrow \Gamma$  where

$$\bar{F}(\alpha, x) = \begin{cases} F(\alpha, x) & \text{for } \alpha \in \Gamma \text{ and } x \in R, \\ F^{-1}(\cdot, x^{-1})(\alpha) & \text{for } \alpha \in \Gamma \text{ and } x \in R^{-1}. \end{cases}$$

The assumption that every function of family  $\{F(\cdot, x)\}_{x \in R}$  is a bijection of the set  $\Gamma$  is very strong. In this case the problem of extensibility according to Remark 1 is reduced to the solutions fulfilling the identity condition. We shall show that this assumption can be released.

First we shall prove the following

**LEMMA.** Let  $R$  be a substructure of the Ehresmann groupoid  $(E; \cdot)$  such that  $R \cup R^{-1} = E$ , let  $\Gamma$  be an arbitrary fixed non-empty set and let  $F$  be an extendable solution of the translation equation defined on the set  $\Gamma \times R$ .

Then

$$(2) \quad F(\Gamma, {}_x e) = \bar{F}(\Gamma, x^{-1}) \quad \text{for every } x \in R,$$

where  $\bar{F}$  is an arbitrary extension of the solution  $F$  defined on the set  $\Gamma \times E$ ,

$$(3) \quad F(\cdot, x) \text{ is a one-to-one mapping from the set } F(\Gamma, {}_x e) \text{ into the set } \Gamma,$$

$$(4) \quad \text{the mapping } \bar{F}: \Gamma \times E \rightarrow \Gamma \text{ being the extension of the solution } F \text{ is uniquely determined.}$$

*P r o o f.* Let  $F$  be an extendable solution of the translation equation defined on the set  $\Gamma \times R$  and let  $\bar{F}$  be an arbitrary extension of  $F$  onto the set  $\Gamma \times E$ .

If  $\alpha \in F(\Gamma, {}_x e)$  then there exists  $\beta \in \Gamma$  such that  $\alpha = F(\beta, {}_x e)$ , thus  $\alpha = F(\beta, x \cdot x^{-1}) = \bar{F}(F(\beta, x), x^{-1})$  so  $\alpha \in \bar{F}(\Gamma, x^{-1})$ . If  $\alpha \in \bar{F}(\Gamma, x^{-1})$  then there exists  $\beta \in \Gamma$  such that  $\alpha = \bar{F}(\beta, x^{-1})$ . Thus  $\alpha = \bar{F}(\beta, x^{-1} \cdot {}_x e) = F(\bar{F}(\beta, x^{-1}), {}_x e)$  since  $e_{x^{-1}} = {}_x e$ , whence  $\alpha \in F(\Gamma, {}_x e)$ . This proves condition (2).

Now, assume that  $\alpha, \beta \in F(\Gamma, {}_x e)$  and  $F(\alpha, x) = F(\beta, x)$ . Then there exists  $\gamma, \delta \in \Gamma$  such that  $\alpha = F(\gamma, {}_x e)$ ,  $\beta = F(\delta, {}_x e)$  and  $F(F(\gamma, {}_x e), x) = F(F(\delta, {}_x e), x)$ . Hence  $\bar{F}(F(F(\gamma, {}_x e), x), x^{-1}) = \bar{F}(F(F(\delta, {}_x e), x), x^{-1})$  thus  $F(F(\gamma, {}_x e), {}_x e) = F(F(\delta, {}_x e), {}_x e)$  or  $F(\gamma, {}_x e) = F(\delta, {}_x e)$ , this means that  $\alpha = \beta$ . Consequently  $F(\cdot, x)$  is a one-to-one mapping on the set  $F(\Gamma, {}_x e)$ .

To prove condition (4) we assume that  $F_1: \Gamma \times E \rightarrow \Gamma$  and  $F_2: \Gamma \times E \rightarrow \Gamma$  are two extensions of the solution  $F$

defined on the set  $\Gamma \times R$ . Then for every  $x \in R$  and  $\alpha \in \Gamma$  we have  $F(F_1(\alpha, x^{-1}), x) = F(\alpha, e_x) = F(F_2(\alpha, x^{-1}), x)$ . It results from condition (2) that  $F_1(\alpha, x^{-1}) \in F(\Gamma, e_x)$  and  $F_2(\alpha, x^{-1}) \in F(\Gamma, e_x)$ , so in virtue of (3) we have  $F_1(\alpha, x^{-1}) = F_2(\alpha, x^{-1})$ . Using  $R \cup R^{-1} = E$  we obtain condition (4), which completes the proof.

Now, we shall be concerned with the main theorem of this paper.

**THEOREM 2.** Let  $R$  be a substructure of the Ehresmann groupoid  $(E; \cdot)$  such that  $R \cup R^{-1} = E$  and let  $\Gamma$  be an arbitrary set. Then the solution  $F$  of the translation equation defined on the set  $\Gamma \times R$  is extendable to the solution  $\bar{F}$  defined on the set  $\Gamma \times E$  if and only if for every  $x \in R$

(5)  $F(\cdot, x)$  is a one-to-one mapping from the set  $F(\Gamma, e_x)$  onto the set  $F(\Gamma, x)$ ,

and then the mapping

$$(6) \quad \bar{F}(\alpha, x) = \begin{cases} F(\alpha, x), & \text{where } \alpha \in \Gamma \text{ and } x \in R, \\ \left[ F(\cdot, x^{-1}) \Big|_{F(\Gamma, e_x)} \right]^{-1}(F(\alpha, x)), & \text{where } \alpha \in \Gamma \text{ and } x \in R^{-1} \end{cases}$$

is a unique extension of the solution  $F$ .

**P r o o f.** Let us notice that for every  $x \in R$

$$(7) \quad F(\Gamma, x) \subset F(\Gamma, e_x).$$

Really, if  $\alpha \in F(\Gamma, x)$  and  $\alpha = F(\beta, x)$  then  $\alpha = F(\beta, x \cdot e_x) = F(F(\beta, x), e_x)$  so  $\alpha \in F(\Gamma, e_x)$ .

Now suppose  $F$  to be an extendable solution of the translation equation defined on  $\Gamma \times R$ . It follows from



conditions (3) and (7) that  $F(\cdot, x)$  is a one-to-one mapping from  $F(\Gamma, e_x)$  into  $F(\Gamma, e_x)$ . To prove condition (5) it is enough to show that for arbitrary  $x \in R$  and  $\alpha \in F(\Gamma, e_x)$  there exists  $\eta \in F(\Gamma, e_x)$  such that  $F(\eta, x) = \alpha$ . Since  $\alpha \in F(\Gamma, e_x)$  so there exists  $\beta \in \Gamma$  such that  $\alpha = F(\beta, e_x)$ . Put  $\eta = F(\beta, x^{-1})$ . According to (2)  $\eta \in F(\Gamma, e_x)$ . Besides  $F(\eta, x) = F(F(\beta, x^{-1}), x) = F(\beta, e_x) = \alpha$ , which completes the proof of a necessary condition.

Let  $F: \Gamma \times R \rightarrow \Gamma$  be a solution of the translation equation such that condition (5) is fulfilled. We define a function  $\bar{F}: \Gamma \times E \rightarrow \Gamma$  by means of condition (6). For  $x \in R \cap R^{-1}$  and  $\alpha \in \Gamma$  we have

$$\left[ F(\cdot, x^{-1}) \Big|_{F(\Gamma, e_x)} \right]^{-1} (F(\alpha, e_x)) = F(\alpha, x)$$

since  $F(F(\alpha, x), x^{-1}) = F(\alpha, e_x)$  and  $F(\alpha, x) \in F(\Gamma, e_x)$  according to (7). Considering additionally condition (5) by the fact that  $x^{-1}e = e_x$ ,  $e_x^{-1} = x e$  and  $R \cup R^{-1} = E$  we can notice that the function  $\bar{F}$  is unambiguously defined on the whole set  $\Gamma \times E$ .

It follows from condition (5) that for an arbitrary  $x \in R^{-1}$  we have

$$F(\cdot, x^{-1}): F(\Gamma, e_x) \xrightarrow{\text{bij}} F(\Gamma, e_x),$$

thus

$$\left[ F(\cdot, x^{-1}) \Big|_{F(\Gamma, e_x)} \right]^{-1}: F(\Gamma, e_x) \xrightarrow{\text{bij}} F(\Gamma, e_x).$$

The mapping  $\bar{F}$  defined by (6) has the following property

$$(8) \quad \bar{F}(\cdot, x) : F(\Gamma, e_x) \xrightarrow{\text{bij}} F(\Gamma, e_x) \quad \text{for every } x \in E.$$

It results from the definition of the function  $\bar{F}$  that  $\bar{F} \Big|_{\Gamma \times R} = F$ .

Thus it must be shown that  $\bar{F}$  is a solution of the translation equation. For this purpose we shall distinguish the following cases.

- a)  $(x, y) \in D., \quad x \in R, \quad y \in R^{-1}, \quad x \cdot y \in R;$
- b)  $(x, y) \in D., \quad x \in R^{-1}, \quad y \in R, \quad x \cdot y \in R;$
- c)  $(x, y) \in D., \quad x \in R^{-1}, \quad y \in R^{-1}, \quad x \cdot y \in R^{-1};$
- d)  $(x, y) \in D., \quad x \in R, \quad y \in R^{-1}, \quad x \cdot y \in R^{-1};$
- e)  $(x, y) \in D., \quad x \in R^{-1}, \quad y \in R, \quad x \cdot y \in R^{-1};$
- f)  $(x, y) \in D., \quad x \in R, \quad y \in R, \quad x \cdot y \in R.$

Moreover, if  $(x, y) \in D.$  then  $e_x = y \cdot e$ .

Case a). Let us determine  $F(\bar{F}(\bar{F}(\alpha, x), y), y^{-1})$  and  $F(\bar{F}(\alpha, x \cdot y), y^{-1})$ . We have

$$\begin{aligned} F(\bar{F}(\bar{F}(\alpha, x), y), y^{-1}) &= F(\bar{F}(F(\alpha, x), y), y^{-1}) = \\ &= F\left(\left[F(\cdot, y^{-1}) \Big|_{F(\Gamma, e_y)}\right]^{-1} (F(\alpha, x), y \cdot e)\right), y^{-1}) = \\ &= F(F(\alpha, x), e_x) = F(\alpha, x) \end{aligned}$$

and

$$\begin{aligned} F(\bar{F}(\alpha, x \cdot y), y^{-1}) &= F(F(\alpha, x \cdot y), y^{-1}) = F(\alpha, x \cdot (y \cdot y^{-1})) = \\ &= F(\alpha, x \cdot e) = F(\alpha, x \cdot e_x) = F(\alpha, x). \end{aligned}$$

Since  $F(\bar{F}(\alpha, x), y) \in F(\Gamma, e_y)$  and  $\bar{F}(\alpha, x \cdot y) \in F(\Gamma, e_y)$  therefore applying (5) we get  $\bar{F}(\bar{F}(\alpha, x), y) = \bar{F}(\alpha, x \cdot y)$ .

Case b). Now we determine  $F(F(F(\alpha, x), y), y^{-1})$  and  $\bar{F}(\bar{F}(\alpha, x \cdot y), y^{-1})$  for  $y^{-1} \in R^{-1}$ . Using the equality from case a) we obtain

$$\begin{aligned} F(F(F(\alpha, x), y), y^{-1}) &= F(F(\alpha, x), y \cdot y^{-1}) = F(F(\alpha, x), e_x) = \\ &= F(\bar{F}(\alpha, x), e_x) = \bar{F}(\alpha, x), \end{aligned}$$

because  $F(\alpha, x) \in F(\Gamma, e_x)$ , and  $F(\cdot, e_x) \Big|_{F(\Gamma, e_x)} = \text{id}_{F(\Gamma, e_x)}$ .

However

$$\begin{aligned} F(F(\alpha, x \cdot y), y^{-1}) &= F(F(\alpha, x \cdot y), y^{-1}) = \\ &= \left[ F(\cdot, y) \Big|_{F(\Gamma, e_{y^{-1}})} \right]^{-1} (F(F(\alpha, x \cdot y), y^{-1}e)) = \\ &= \left[ F(\cdot, y) \Big|_{F(\Gamma, ye)} \right]^{-1} F(F(\alpha, x \cdot y), e_y) = \\ &= \left[ F(\cdot, y) \Big|_{F(\Gamma, e_x)} \right]^{-1} F(\alpha, x \cdot y) = \\ &= \left[ F(\cdot, y) \Big|_{F(\Gamma, e_x)} \right]^{-1} F(\bar{F}(\alpha, x), y) = \bar{F}(\alpha, x), \end{aligned}$$

because  $F(\alpha, x) \in F(\Gamma, e_x)$ .

Since  $F(F(\alpha, x), y) \in F(\Gamma, e_y) = F(\Gamma, y^{-1}e)$  and

$F(\alpha, x \cdot y) \in F(\Gamma, y^{-1}e)$  therefore in virtue of (8) we get

$$F(F(\alpha, x), y) = F(\alpha, x \cdot y).$$

Case o). For  $x \in R^{-1}$ ,  $y \in R^{-1}$  and  $x \cdot y \in R^{-1}$  we have

$$\begin{aligned} F(F(\alpha, x), y) &= \left[ F(\cdot, y^{-1}) \Big|_{F(\Gamma, e_y)} \right]^{-1} (F(F(\alpha, x), ye)) = \\ &= \left[ F(\cdot, y^{-1}) \Big|_{F(\Gamma, e_y)} \right]^{-1} (F(\alpha, x)) = \\ &= \left\{ \left[ F(\cdot, y^{-1}) \Big|_{F(\Gamma, e_y)} \right]^{-1} \circ \left[ F(\cdot, x^{-1}) \Big|_{F(\Gamma, e_x)} \right]^{-1} \right\} (F(\alpha, xe)) = \end{aligned}$$

$$\begin{aligned}
&= \left[ F(\cdot, x^{-1}) \Big|_{F(\Gamma, e_x)} \circ F(\cdot, y^{-1}) \Big|_{F(\Gamma, e_y)} \right]^{-1} (F(\alpha, x e)) = \\
&= \left[ F(\cdot, y^{-1} \cdot x^{-1}) \Big|_{F(\Gamma, e_y)} \right]^{-1} (F(\alpha, x e)) = \\
&= \left[ F(\cdot, (x \cdot y)^{-1}) \Big|_{F(\Gamma, e_y)} \right]^{-1} (F(\alpha, x e)) = \\
&= \bar{F}(\alpha, x \cdot y),
\end{aligned}$$

since  $F(\Gamma, y e) = F(\Gamma, e_x)$ ,  $x \cdot y e = x e$  and  $e_{x \cdot y} = e_y$  for  $(x, y) \in D$ .

In cases d) and e) we argue in a similar way, using a) and b) respectively. Case f) is obvious.

From the above consideration by (4) we obtain that the solution  $F$  of the translation equation defined on the set  $\Gamma \times R$  and fulfilling condition (5) is uniquely extendable to the solution  $\bar{F}$  defined by (6) on the set  $\Gamma \times E$ .

The above theorem yields a generalization of theorem 1 from [2]. In paper [2] theorem 1 is formulated for a sub-semigroup  $P$  of a group  $(G; \cdot)$  such that  $P \cup P^{-1} = G$ . Notice that if  $e_x = x e$  then the function  $F(\cdot, x)$  is a bijection on its codomain. However, if the structure  $R$  has the only one unit then condition (5) is equivalent to the fact that  $\{F(\cdot, x)\}_{x \in R}$  is a family of functions being bijections on the common codomain.



## R e f e r e n c e s

- [1] Grząślewicz A., On the solutions of the generalizing equation of homomorphism, Rocznik Naukowo-Dydaktyczny WSP w Krakowie /Prace Mat./ 61 (1977), p.31-38.
- [2] Mach A., Z.Moszner, Sur les prolongements de la solution de l'équation de translation, Zeszyty Naukowe UJ (to appear).